

**SLang - the Next Generation**



## **Tutorial**

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## 0.1 Analysis of imported FE mesh

This example shows the import and analysis of a tetrahedral volume mesh generated by `gmsh`. The geometry is defined as shown in Fig. ???. It is then meshed with 5515 4-node tetrahedral elements. The structure is

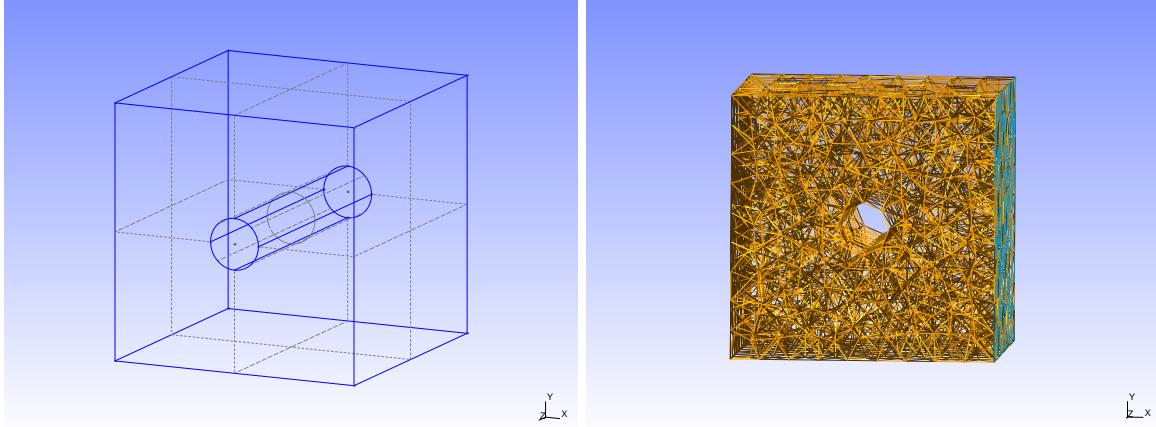


Figure 1: Geometry of block with cylindrical hole

supported on one side. The support elements are defined as physical group in `gmsh`. On the opposite side, a transverse load is applied (in  $y$ -direction).

The procedure to arrive at the solution of this problem is given in the following script.

```

1 --]]
2 SLangTNG
3 Test for Finite Element analysis
4 FE model imported from Gmsh
5 (c) 2009 Christian Bucher, CMSD-VUT
6 --]]
7
8
9 -- import the model (Tetrahedra vor volumes, triangles for surfaces) and set all DOF's to available
10 struc=tngfem.TNGStructureImportGmsh("block.msh")
11 struc:SetAvailDof(1, 1, 1, 1, 1, 1)
12
13 -- Get the element group containing the support surface and convert to node group
14 support=struc:GetGroup(1)
15 nsup=support:ToNodeGroup(101)
16
17 -- remove all available DOF's for support
18 struc:SetAvailDof(0, 0, 0, 0, 0, 0, nsup:GetMemberList())
19
20 -- Get the element group carrying the distributed load (triangles)
21 load=struc:GetGroup(2)
22 loadList = load:GetMemberList()
23
24 -- Get the element group defining the body (tetrahedra)
25 evol=struc:GetGroup(3)
26 evolList = evol:GetMemberList()
27
28 -- Define section and material properties (Gmsh provides only the mesh)
29 ss=struc:AddSection(301, "SHELL", 0, 0.01)
30 ss:SetColor(0,200,200,255)
31 struc:SetSection(301, loadList)
32 struc:SetSection(301, support:GetMemberList())
33
34 s=struc:AddSection(300, "VOLUME", 0)
35 s:SetColor(255,0,0,255)
36 struc:AddMaterial(800, "LINEAR-ELASTIC", 1, .3, 1)
37 struc:SetMaterial(800, evolList)
38 struc:SetSection(300, evolList)
39
40 -- Assign global DOF numbers
41 nd=struc:GlobalDof()
```

```

42 — define distributed load in global y-direction
43 force=tmath.ReadMatrix({{0},{1},{0}})
44
45 — Assemble global load vector
46 F=struct:GlobalForce(force, loadList)
47
48 — Assemble global stiffness matrix
49 K=struct:SparseStiffness(evolList)
50
51 — Solver for displacements
52 U=K:Solve(F)
53
54 — Show deformed structure (only volume elements are set visible)
55 struc:SetDofDisplacements(U)
56
57 vis=tnggraphics.TNGVisualize(40, 40, 1100, 800, "Structure")
58 vis:Lighting(true)
59 vis:Perspective(true)
60 vis:SetAngles(20,-20,0)
61 vis:Draw(struc, .05)
62
63 — Add a vector plot showing the displacements
64 U2 = struc:GetAllDisplacements()
65 vis:Vector(struc, U2, .05)
66 vis:File("block_def.pdf")
67 vis:File("block_def.png")
68
69 — [[
70 Compute and visualize stresses
71 The stresses are computed in ElementStressresult(k...). Here
72 the meaning of k is:
73   0 v.Mises stress
74   1 s_xx
75   2 s_yy
76   3 s_zz
77   4 t_xy
78   5 t_xz
79   6 t_yz
80 — ]]
81 struc:SetVisible(false)
82 struc:SetVisible(true, evolList)
83 sv=tnggraphics.TNGSuperVisualize(40, 40, 1100, 800, "Stresses")
84 for i=1,6 do
85   v=sv:AddVisualize("Stress"..i, math.mod(i-1,2)==0)
86   stress = struc:ElementStress(i)
87   v:Perspective(true)
88   v:Palette(true)
89   v:Lighting(true)
90   v:SetAngles(20,-10,0)
91   v:ElementResult(struc, stress, true, 0.05)
92   v:Zoom(1.3)
93 end
94 sv:File("block_stress.pdf", 3)

```

The deformed structure is shown in Fig. ???. The stresses are shon in Fig. ???.

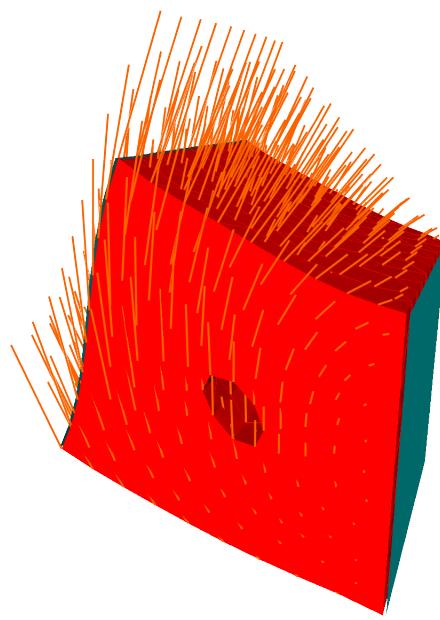


Figure 2: Deformation of block with cylindrical hole

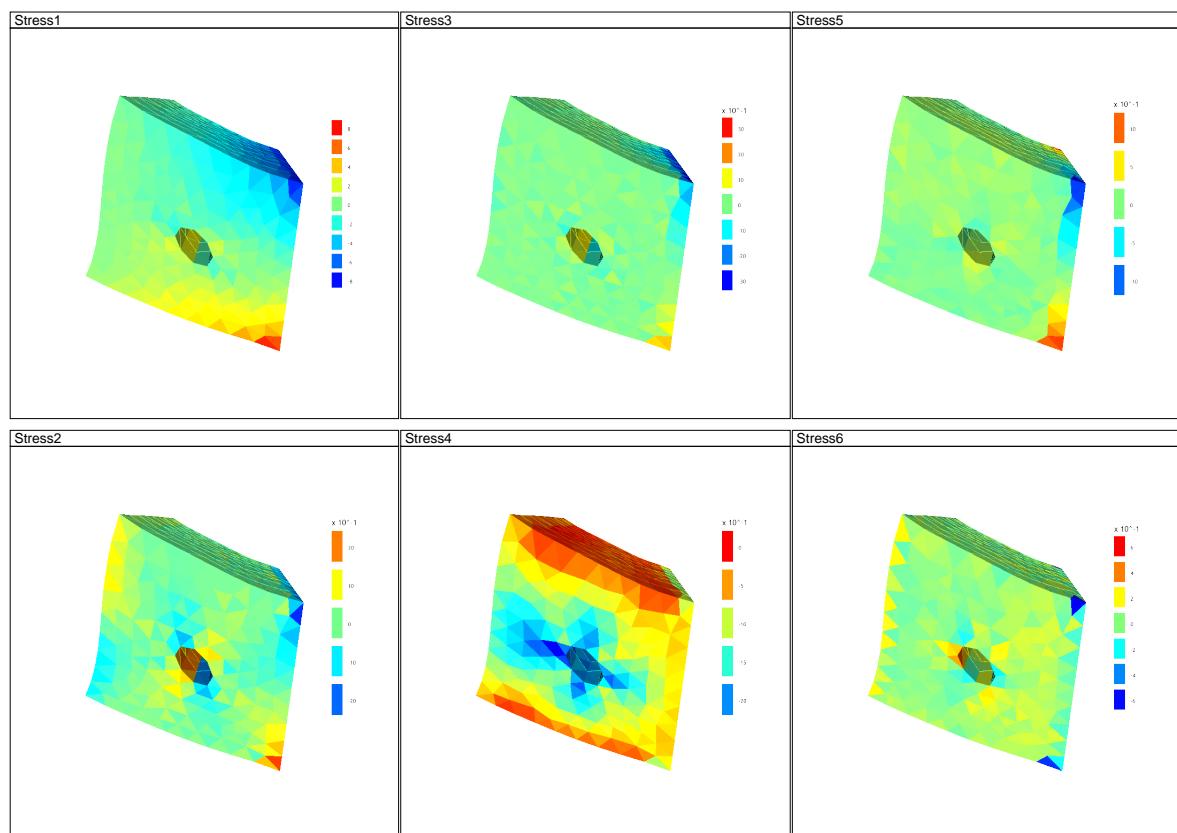


Figure 3: Stresses in block with cylindrical hole